

Parameterisable damper actuator in the IP66 protective housing for adjustment of dampers in industrial plants and building installations

- Air damper size up to approx. 8 m²
- Nominal torque 40 Nm
- Nominal voltage AC/DC 24 V
- Control Modulating DC (0)2...10 V Variable
- Position feedback DC 2...10 V Variable
- Optimum weather protection for use outdoors (for use in ambient temperatures up to -40°C, there is a separate actuator available with built-in heater ex works)



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Electrical data	Nominal voltage	AC/DC 24 V		
	Nominal voltage frequency	50/60 Hz		
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V		
	Power consumption in operation	4 W		
	Power consumption in rest position	1.5 W		
	Power consumption for wire sizing	7 VA		
	Power consumption for wire sizing note	Imax 20 A @ 5 ms		
	Connection supply / control	Terminals 4 mm² (cable Ø 410 mm, 4-wire)		
	Parallel operation			
	rarallel operation	Yes (note the performance data)		
Functional data	Torque motor	Min. 40 Nm		
	Torque variable	25%, 50%, 75% reduced		
	Positioning signal Y	DC 010 V		
	Positioning signal Y note	Input impedance 100 kΩ		
	Control signal Y variable	Open-close		
		3-point (AC only)		
		Modulating (DC 032 V)		
	Operating range Y	DC 210 V		
	Operating range Y variable	Start point DC 0.530 V		
		End point DC 2.532 V		
	Position feedback U	DC 210 V		
	Position feedback U note	Max. 0.5 mA		
	Position feedback U variable	Start point DC 0.58 V		
		End point DC 2.510 V		
	Position accuracy	±5%		
	Direction of motion motor	Selectable with switch 0 / 1		
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) / 1		
		(cw rotation)		
	Direction of motion variable	Electronically reversible		
	Manual override	Gear disengagement with push-button, can be		
		locked (under protective housing)		
	Angle of rotation	Max. 95°		
	Angle of rotation note	can be limited on both sides with adjustable		
		mechanical end stops		
	Running time motor	150 s / 90°		
	Motor running time variable	90150 s		
	Adaption setting range	manual		
	Adaption setting range variable	No action		
		Adaption when switched on		
		Adaption after pushing the gear disengagement		
		button		
	Override control	MAX (maximum position) = 100%		
		MIN (minimum position) = 0%		
		ZS (intermediate position, AC only) = 50%		
	Override control variable	MAX = (MIN + 32%)100%		
		MIN = 0%(MAX - 32%)		
		ZS = MINMAX		
	Sound power level motor	45 dB(A)		
	Spindle driver	Universal spindle clamp 1426.7 mm		
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Mechanically, pluggable

Position indication

# Damper actuator, IP66, parameterisable, Modulating, AC/DC 24 V, 40 Nm



## **Technical data**

#### Safety

Protection class IEC/EN	III Safety extra-low voltage		
Protection class UL	UL Class 2 Supply		
Degree of protection IEC/EN	IP66		
Degree of protection NEMA/UL	NEMA 4, UL Enclosure Type 4		
EMC	CE according to 2004/108/EC		
Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14		
Certification UL	cULus according to UL 60730-1A, UL 60730-2-		
	14 and CAN/CSA E60730-1:02		
Mode of operation	Type 1		
Rated impulse voltage supply / control	0.8 kV		
Control pollution degree	4		
Ambient temperature	-3050°C		
Ambient temperature note	-4050°C for actuator with integrated heating		
Non-operating temperature	-4080°C		
Ambient humidity	100% r.h.		
Maintenance	Maintenance-free		
Weight approx.	4.2 kg		

## Safety notes



Weight

- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- Junction boxes must at least correspond with enclosure IP degree of protection!
- The cover of the protective housing may be opened for adjustment and servicing.
   When it is closed afterwards, the housing must seal tight (see installation instructions).
- The device may only be opened in the manufacturer's factory. It does not contain any parts that can be replaced or repaired by the user.
- The cables must not be removed from the device installed in the interior.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed
  of as household refuse. All locally valid regulations and requirements must be
  observed.
- The actuator is not designed for applications where chemical influences (gases, fluids) are present or for utilisation in corrosive environments in general.
- The actuator may not be used in plenary applications (e.g. suspended ceilings or raised floors).
- The materials used may be subjected to external influences (temperature, pressure, construction fastening, effect of chemical substances, etc.), which cannot be simulated in laboratory tests or field trials. In case of doubt, we definitely recommend that you carry out a test. This information does not imply any legal entitlement. Belimo will not be held liable and will provide no warranty.
- If cables which are not authorised for UL (NEMA) Type 4 applications are guided out
  of the unit, then flexible metallic cable conduits or suitable threaded cable conduits
  of equal value are to be used.



### **Product features**

Fields of application

The actuator is particularly suitable for utilisation in outdoor applications and is protected against the following weather conditions:

- UV radiation
- rain / snow
- dirt / dust
- Humidity

- Changing atmosphere / frequent and severe temperature fluctuations

(recommendation: use the actuator with integrated factory-installed heating which can

be ordered separately to prevent internal condensation)

Mode of operation

The actuator is connected with a standard modulating signal of DC 0...10V and drives to the position defined by the positioning signal. Measuring voltage U serves for the electrical display of the damper position 0...100% and as slave control signal for other actuators.

Parameterisable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

Simple direct mounting

Simple direct mounting on the damper spindle with an universal spindle clamp, supplied with an anti-rotation device to prevent the actuator from rotating.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

The housing cover must be removed for manual override.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

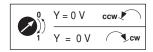
Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops. Standard setting 0 ... 90°. The housing cover must be removed to set the angle of rotation.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal.



## Adaption and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).

Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

## **Accessories**

	Description	Type
Electrical accessories	Auxiliary switch, add-on, 1 x SPDT	S1A
	Auxiliary switch, add-on, 2 x SPDT	S2A
	Feedback potentiometer 140 Ohm, add-on	P140A
	Feedback potentiometer 200 Ohm, add-on	P200A
	Feedback potentiometer 500 Ohm, add-on	P500A
	Feedback potentiometer 1 kOhm, add-on	P1000A
	Feedback potentiometer 2.8 kOhm, add-on	P2800A
	Feedback potentiometer 5 kOhm, add-on	P5000A
	Feedback potentiometer 10 kOhm, add-on	P10000A
	Signal converter voltage/current, supply AC/DC 24V	Z-UIC
	Digital position indicator for front-panel mounting, 099%, front mass $72 \times 72 \text{ mm}$	ZAD24
	Range controller for wall mounting, adjustable electron. Min./max. angle of rotation limitation	SBG24
	Positioner for wall mounting, range 0100%	SGA24
	Positioner in a conduit box, range 0100%	SGE24



## **Accessories**

Туре
SGF24
CRP24-B1
ZK1-GEN
ZK2-GEN
Туре
Z-KB-PG11
Туре
ZTH EU
MFT-P
MFT-C

# **Electrical installation**



**Notes** 

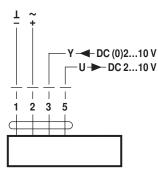
**Service Tools** 

Mechanical accessories

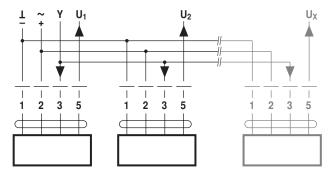
· Connection via safety isolating transformer.

### Wiring diagrams

AC/DC 24 V, modulating



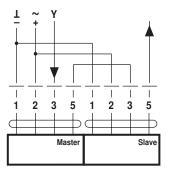
## Parallel operation



#### Notes

- A maximum of eight actuators can be connected in parallel.
- Parallel operation is permitted only on non-connected axes.
- Do not fail to observe performance data with parallel operation.

Wiring diagram piggyback operation (mechanically coupled actuators)



## Notes

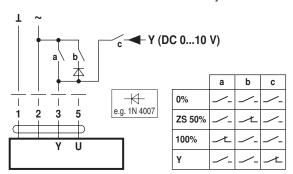
- A maximum of two actuators can be connected in Master-Slave operation.
- The Master-Slave operation is permitted only on one fixed spindle or on two mechanically coupled spindles.
- The programming of the Master actuator is adopted by the Slave actuator.



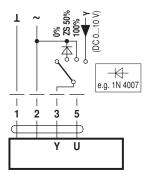
## **Functions**

## Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts

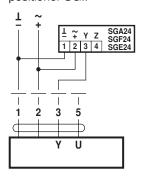


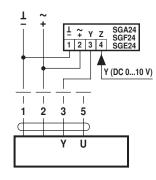
Override control with AC 24 V with rotary switch

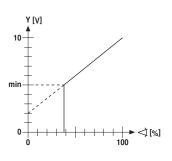


Remote control 0...100% with positioner SG..

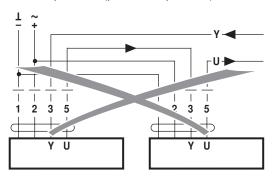
Minimum limit with positioner SG..



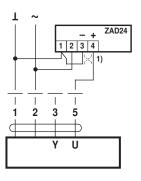




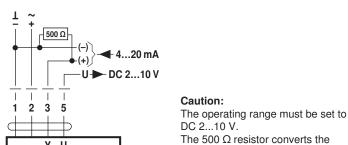
Follow-up control (position-dependent)



Position indication

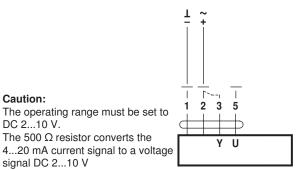


Control with 4...20 mA via external resistor



signal DC 2...10 V

Functional check



(1) Adapting the direction of rotation

## **Procedure**

- 1. Connect 24V to connections 1 and 2
- 2. Disconnect connection 3:
- with direction of rotation 0:
- Actuator rotates to the left
- with direction of rotation 1: Actuator rotates to the right
- 3. Short-circuit connections 2 and 3:
- Actuator runs in opposite direction

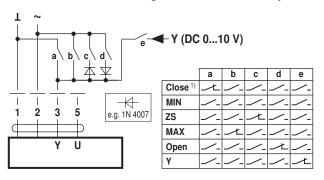


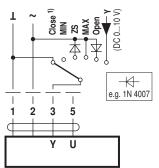
## **Functions**

## Functions for actuators with specific parameters (Parametrisation with PC-Tool necessary)

Override control and limiting with AC 24 V with relay contacts

Override control and limiting with AC 24 V with rotary switch

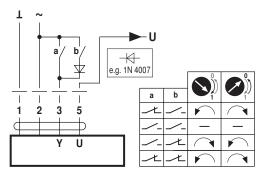




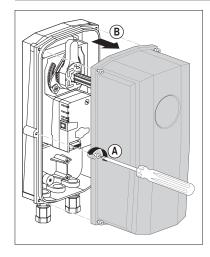
1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

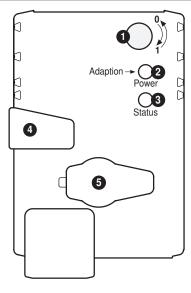
Control open-close

Control 3-point



## Operating controls and indicators





1 Direction of rotation switch

Switch over: Direction of rotation changes

2 Push-button and LED display green

Off: No power supply or malfunction

On: In operation

Press button: Triggers angle of rotation adaptation,

followed by standard mode

3 Push-button and LED display yellow

Off: Standard mode

On: Adaptation or synchronising process active

Press button: No function

4 Gear disengagement button

Press button: Gear disengages, motor stops,

manual override possible

Release button: Gear engages, synchronisation starts,

followed by standard mode

5 Service plug

For connecting parameterisation and service tools

#### Check power supply connection

2 Off and 3 On Possible wiring error in power supply



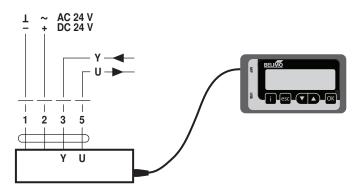
# Service



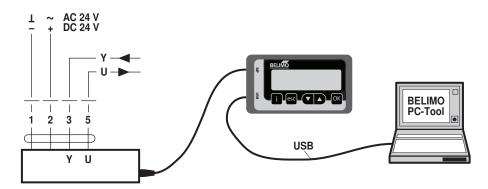
**Notes** 

 The actuator can be parameterised by PC-Tool and ZTH EU via the service socket.

## Service Tools connection ZTH EU connection



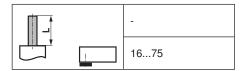
PC-Tool connection

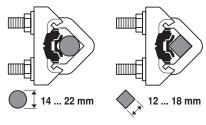


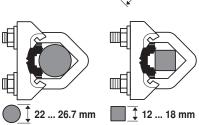


# Dimensions [mm]

# Spindle length







# **Dimensional drawings**

